

CLAIMS

We claim:

1. A robotic frame for supporting a covering to provide a
5 turkey decoy, comprising:

a mobile carriage having means mounted thereon for traversing
over the ground surface;

at least one post projecting upwardly from said carriage;

a central frame member supported on said post;

10 a first neck supporting frame portion mounted on said central
frame portion and projecting from one first end thereof;

a second frame portion secured to said central frame portion
and projecting from a second end thereof opposite said one first
end; and

15 a first pair of arms mounted on said central frame member for
supporting wing defining portions of the decoy.

2. The robotic frame as defined in claim 1, wherein at least
one of said first and second frame portions and said first pair of
arms are movably mounted on said central frame portion.

20 3. The robotic frame as defined in claim 2, wherein each of
said first and second frame portions and said first pair of arms
are pivotally mounted on said central frame portion.

4. The robotic frame as defined in claim 1, including a remotely controlled motor means mounted on said carriage and means drivingly connecting the same to said ground traversing means.

5. The robotic frame as defined in claim 1, including means on a portion thereof for reorienting at least a portion thereof to selectively change the direction that the turkey decoy faces.

6. The robotic frame as defined in claim 5, including means pivotally mounting said central frame portion on said post for rotation about a vertical axis and thereby providing said means to change the direction that the turkey decoy faces.

7. The robotic frame as defined in claim 6, including motor means carried by said frame and drivingly connected to controllably rotate said central frame portion on said post.

8. The robotic frame as defined in claim 5, including motor means mounted on said mobile carriage, means drivingly connecting said motor to said ground traversing means thereon and means for selectively controlling said motors to cause said mobile carriage to travel over the ground surface and change the direction of travel and thereby reorient the turkey decoy to face a desired direction.

9. The robotic frame as defined in claim 1, wherein said

first neck defining portion of the frame is pivotally mounted on said central frame portion.

10. The robotic frame as defined in claim 1, wherein said first pair of arms are pivotally mounted on said central frame portion for movement relative thereto.

11. The robotic frame as defined in claim 10, wherein said first pair of arms are pivotally mounted on said central frame portion.

12. The robotic frame as defined in claim 1, including a second pair of arms and means movably mounting the same on said central frame portion.

13. The robotic frame as defined in claim 12, including means interconnecting said first and second pair of arms for inter relating movement of the same.

14. The robotic frame as defined in claim 1, wherein said second frame portion defines a tail of the turkey decoy and includes a pair of members moveable relative to one another for selectively varying the width of the tail of the decoy.

15. The robotic frame as defined in claim 14, including means pivotally mounting said pair of members on said central frame

portion to pivot about a generally horizontal axis and change to inclination of the tail of the decoy.

16. The robotic frame as defined in claim 1, including a flexible covering mounted on said frame and thereby providing a mobile turkey decoy having a body, a neck with a head thereon projecting from one end of the body and a tail projecting from the other end of the body and wherein each of the head and tail are moveable up and down in a vertical direction.

17. The turkey decoy as defined in claim 1, including motor means on said frame and drivingly connected to said movable frame portions for selectively moving the same.

18. The turkey decoy as defined in claim 1, including a servo motor mounted on said central frame portion, wherein each of said first and second frame portions and said first pair of arms are movable relative to said central frame portion and means drivingly connecting said motor to move the same in co-ordinated inter related relationship.

19. The turkey decoy as defined in claim 18, including an RF receiver mounted thereon and connected to said motor for use in remote control of the same.

20. The turkey decoy as defined in claim 1, including a

second pair of arms and means moveably mounting the same on said central frame portion and located to engage a turkey back defining portion for moving the same.

21. The turkey decoy as defined in claim 20, including means
5 interconnecting said first and second pair of arms to inter-relate movement of the same.

22. The turkey decoy as defined in Claim 1, including a
central processing unit electrically connecting to and
10 communicating with said servo units for selecting programming movement sequences programmable by a keypad or insertion of a removable readable memory device.

23. The turkey decoy as defined in claim 1, including a
speaker and recording device activated by a timer device or remote
15 unit.